

Guided Wave Tomography

Remo Ribichini, Peter Huthwaite Francesco Simonetti and Peter Cawley



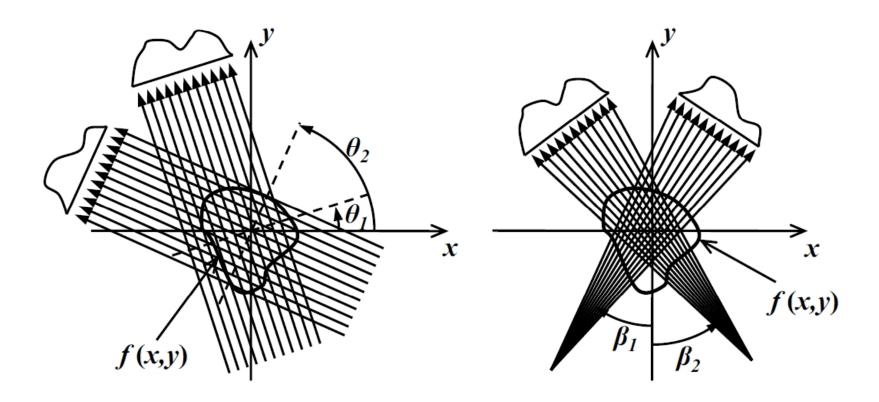
Current Guided Wave Techniques For Pipe Inspection:

Allow Defect Detection (axial and circumferential position)Allow Defect Size Estimation

Further Goal: percentage depth map Mapping of Corrosion Under Supports

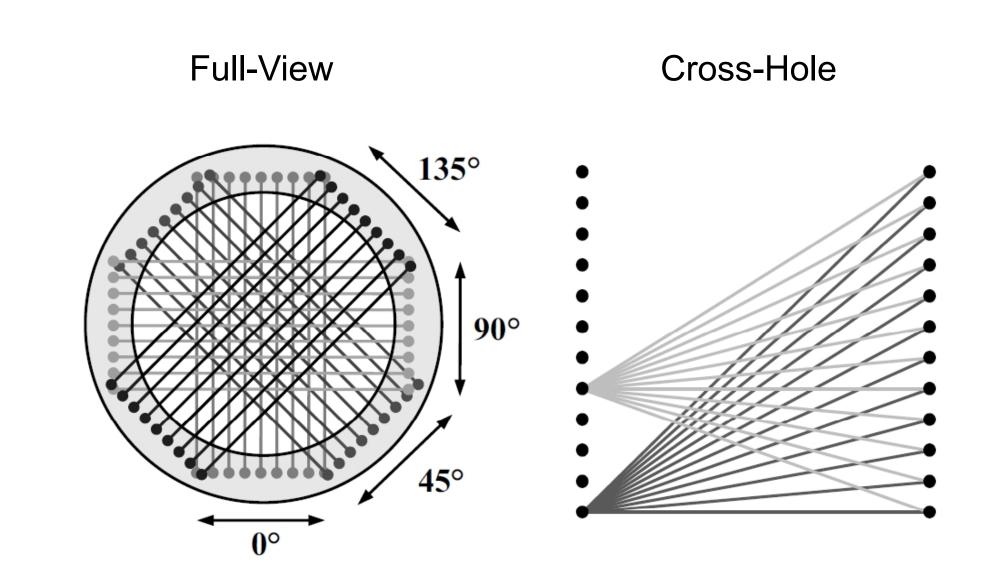


Tomography

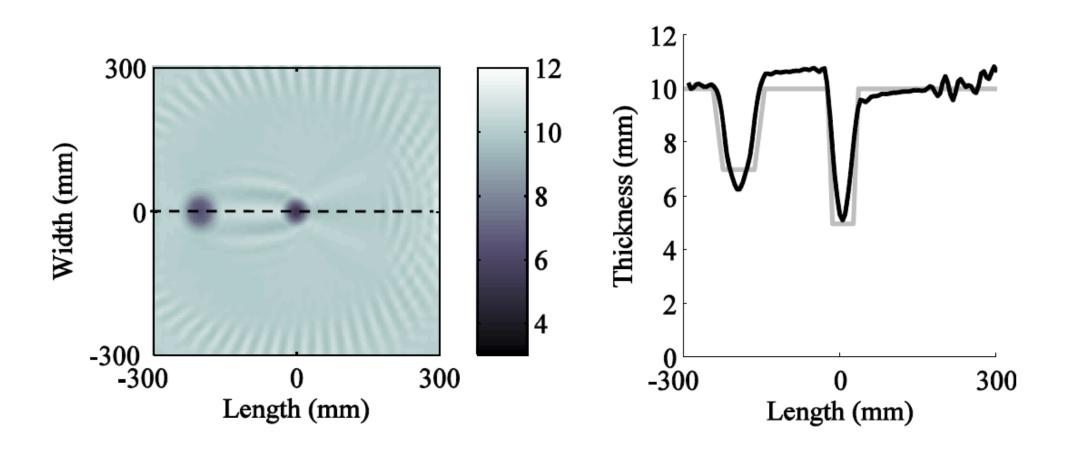


Figures Courtesy of Dr P. Belanger





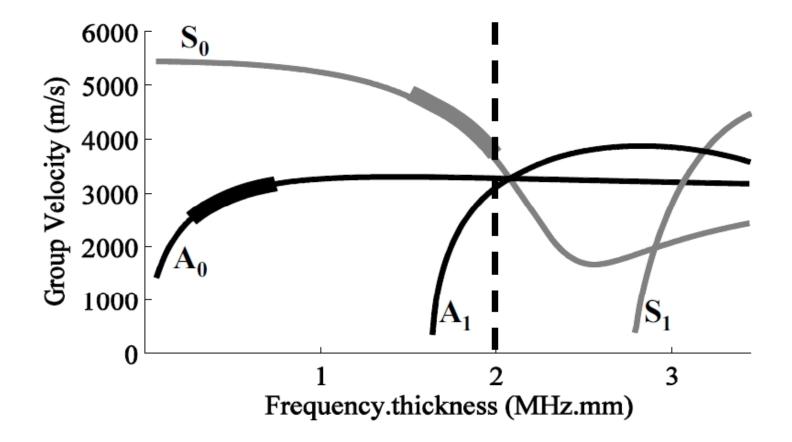




Figures Courtesy of Dr P. Belanger



Guided Wave Tomography



Figures Courtesy of Dr P. Belanger

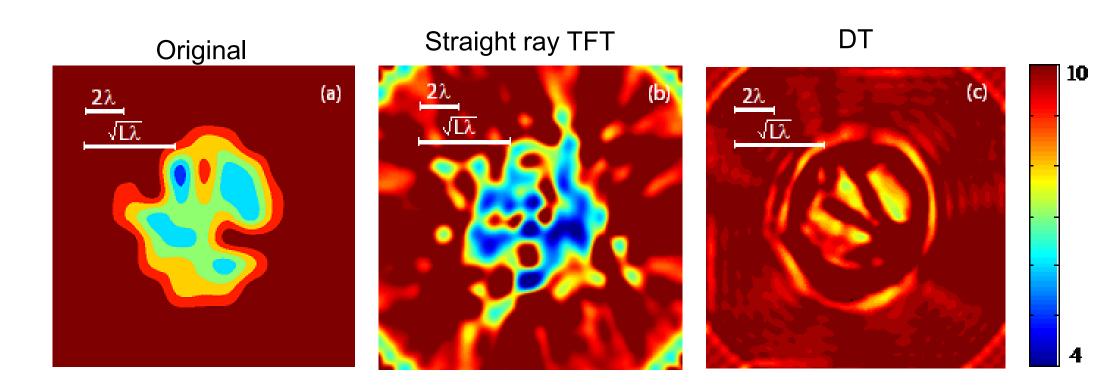


Two Main Tomography Techniques:

- •Time of Flight Tomography (TFT) \longrightarrow Ray Approximation $d >> \lambda$
- •Diffraction Tomography (DT) $\rightarrow d \sim \lambda$



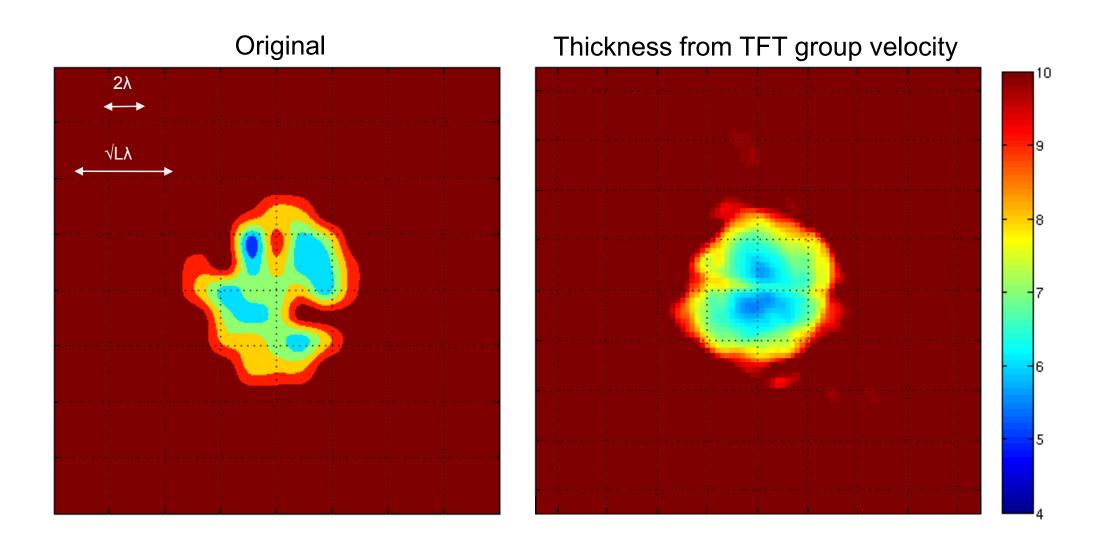
Previous Results



Circular array with 128 transducers. 10mm thickness aluminium plate f=50kHz λ =38mm



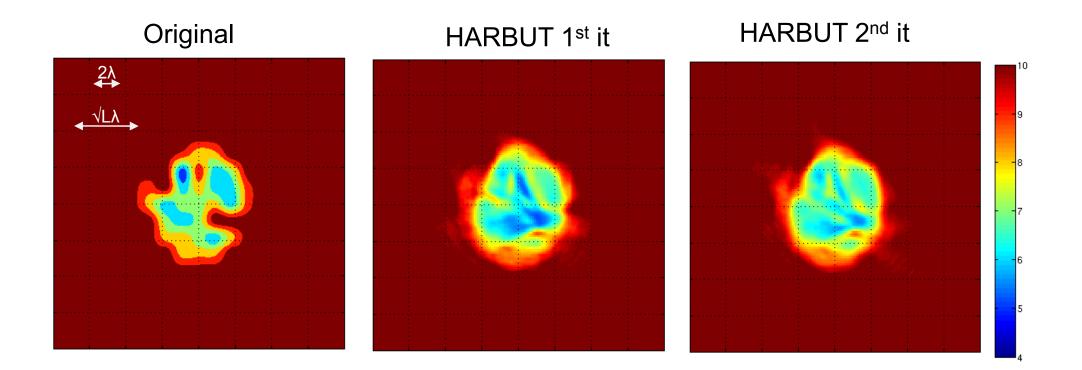
TFT with dispersion





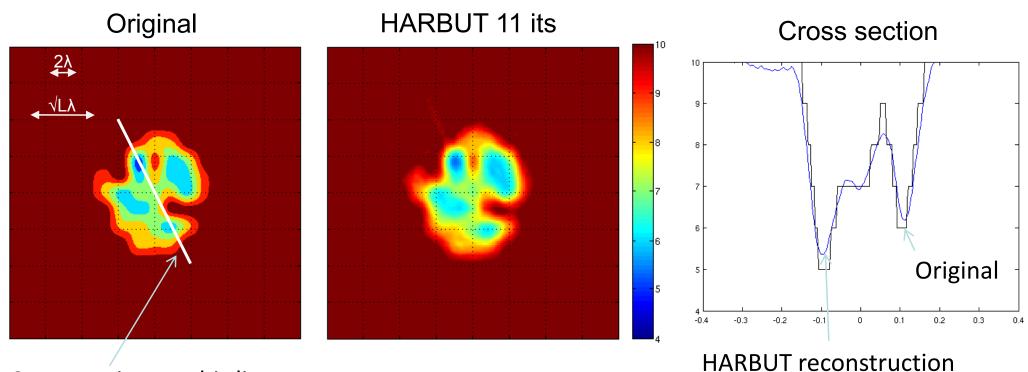
HARBUT

(Hybrid Algorithm for Robust Breast Ultrasound Tomography)





Many HARBUT iterations



Cross section on this line



First Trial

